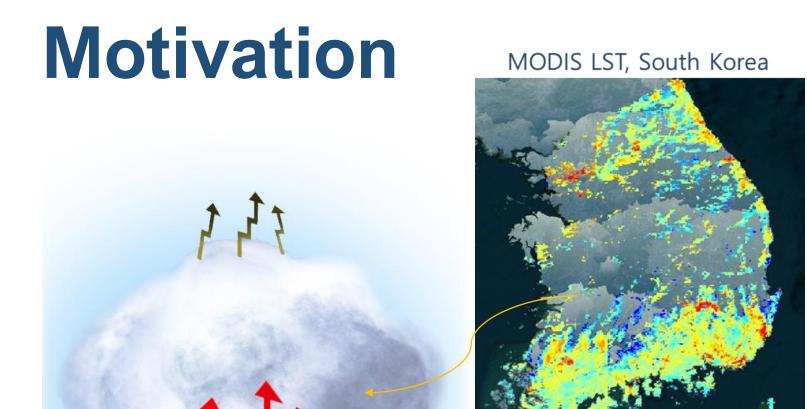
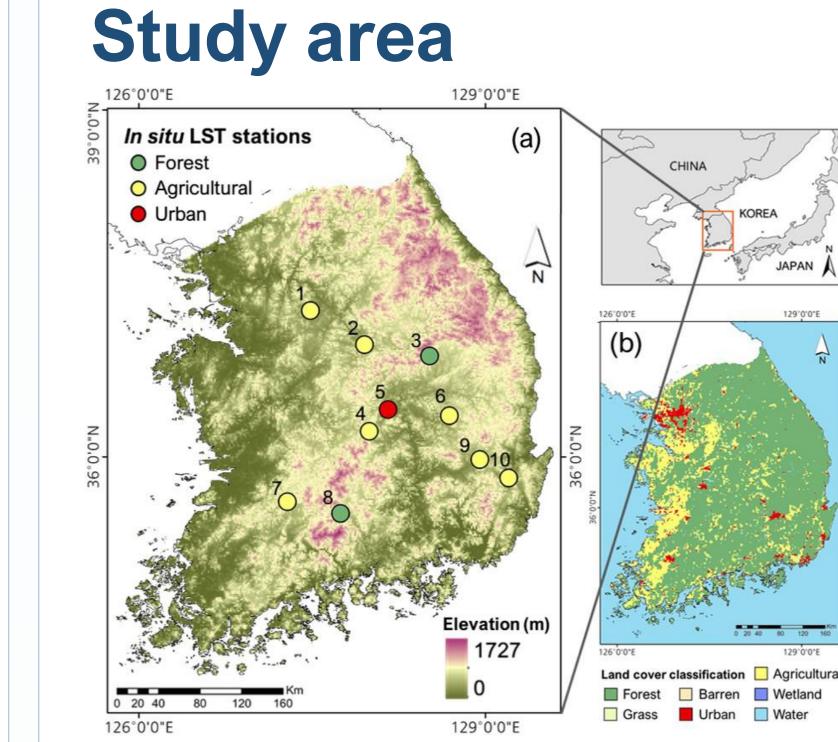
Estimation of All-Weather 1 km MODIS Land Surface Temperature for Humid Summer Days

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Data and Input Variables

We used eight AMSR2 BTs, three ACPs (i.e., MAST, Yast, and theta), and six auxiliary variables for the LST estimations. The MYD11A1 LST data, which have 1 km spatial resolution, from 2013–2018 were downloaded.

Туре	Variables	Acronym		
	36.5 GHz horizontal polarization	36H		
	36.5 GHz vertical polarization	36V		
	23.8 GHz horizontal polarization	23H		
AMSR2 BT	23.8 GHz vertical polarization	23V		
AMISK2 DI	18.7 GHz horizontal polarization	18H		
	18.7 GHz vertical polarization	18V		
	10.7 GHz horizontal polarization	10H		
	10.7 GHz vertical polarization	10V		
	Mean annual LST (K)	MAST		
Annual cycle parameters	Mean annual amplitude of LST (K)	YAST		
	Phase shift relative to spring equinox on the Northern	theta		
	hemisphere			
	Elevation (m)	Elev		
	Impervious surface fraction (%)	Imp		
Auxiliary variables	Latitude (°)	Lat		
Auxiliary valiables	Longitude (°)	Lon		
	Converted day of year	DOY		
	Year as a discrete value	Year		



Land surface temperature (LST) is used as a critical indicator for various environmental issues because it links land surface fluxes with the surface Moderate-resolution atmosphere. imaging spectroradiometers (MODIS) 1 km LSTs have been widely utilized but have the serious limitation of not being provided under cloudy weather conditions. In this study, we propose two schemes to estimate all-weather 1 km Aqua MODIS daytime (1:30 p.m.) and nighttime (1:30 a.m.)

The study area is the mainland of South Korea. In South Korea, summers can often be scorching, causing a variety of disasters. A total of 10 automated surface observing systems (ASOSs) were selected for in situ reference LST data locations.

Scheme 1 (S1) is a two-step approach that first estimates 10 km LSTs and then

conducts the downscaling of LSTs from 10 km to 1 km based on random forest.

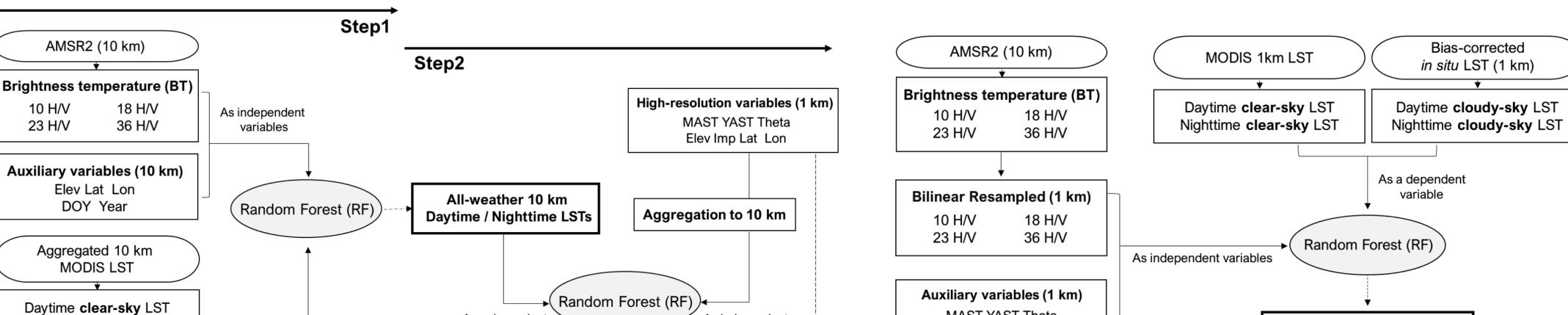
• Study periods: July-August, 2013-2018

LST Processing

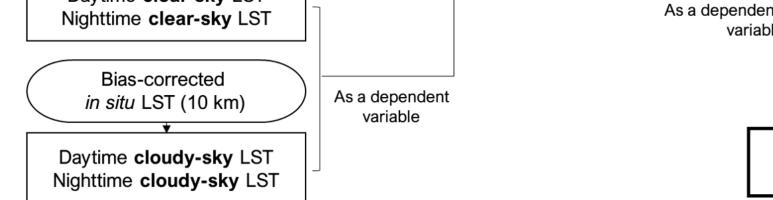
- The 1 km MODIS LSTs with quality control (QC) flags of 'cloud' were considered to be pixels under cloudy sky conditions.
- We fitted in situ LST and MODIS LST under clear sky conditions using polynomial regression by station to biascorrect in situ LSTs for both daytime and nighttime.

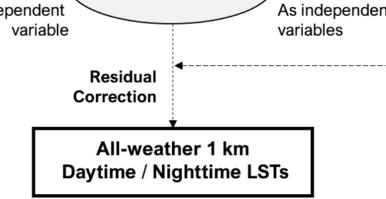
Methods: Scheme1 (S1)

Methods: Scheme2 (S2)



- Clear sky 1 km MODIS LSTs were aggregated to 10 km based on the 10 km AMSR2 grid area.
- We also fitted the in situ LSTs and the 10 MODIS LSTs under clear sky km conditions using polynomial regression



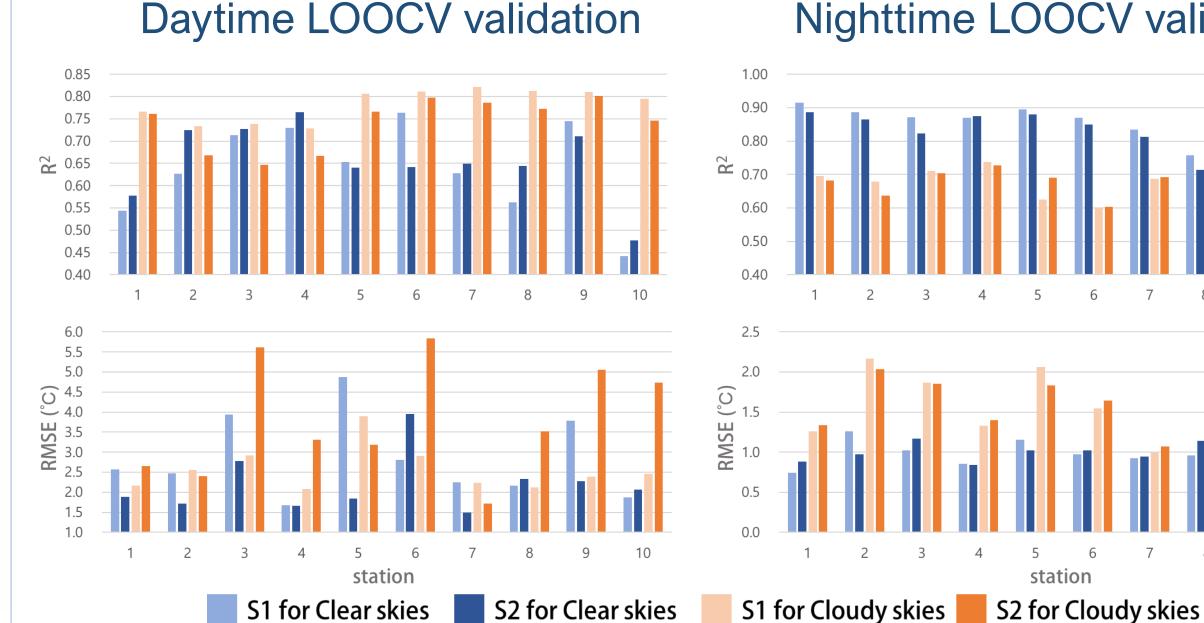


MAST YAST Theta Elev Imp Lat Lon DOY Year

All-weather 1 km Daytime / Nighttime LSTs

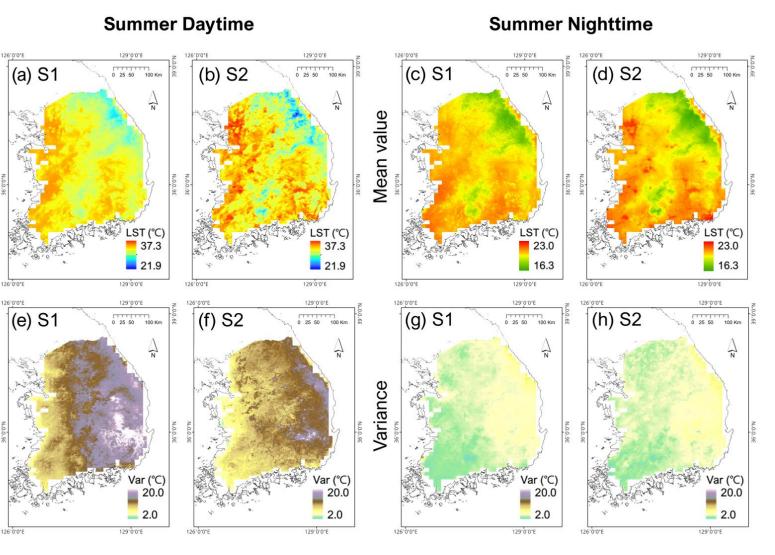
Scheme 2 (S2), a one-step algorithm, directly estimates the 1 km all-weather LSTs. For S1 and S2, both clear sky MODIS LSTs and the bias-corrected in situ LSTs under cloud sky conditions were used as a dependent variable to provide the models with the LST characteristics for clear and cloudy skies.

Results: Two-scheme (S1 and S2) Comparisons

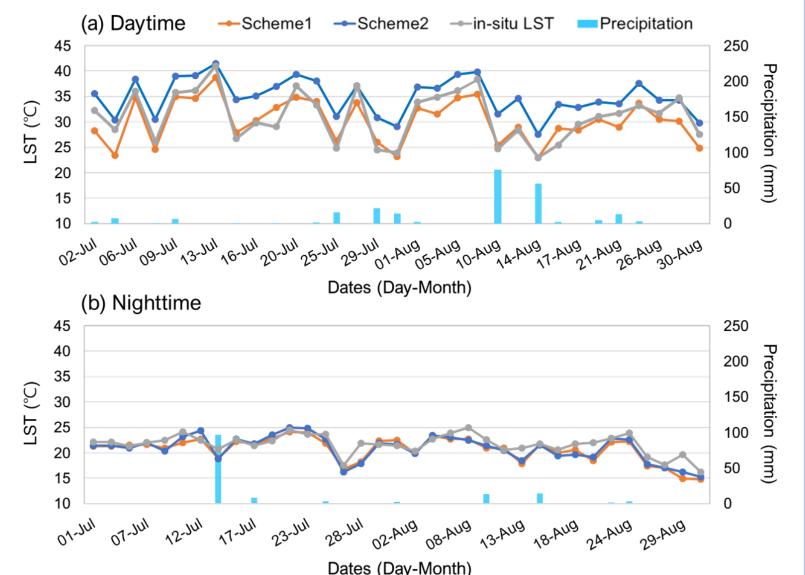


Nighttime LOOCV validation

Spatial distribution of all-sky LSTs



Time-series of the estimated LSTs and 1 km bias-corrected in situ LSTs with precipitation at station9



In the daytime, S2 generally simulated LSTs higher in

The leave one-station out cross-validation (LOOCV) results show that the performance of S2 was better than S1 in clear-sky daytime. However, in cloudy sky daytime, S1 simulated low LSTs better than S2, with an average root mean squared error (RMSE) of 2.6°C compared to an average RMSE of 3.8 °C over 10 stations. At nighttime, S1 and S2 demonstrated no significant difference in performance both under clear and cloudy sky conditions.

urban and agricultural areas than S1. At nighttime, the S1 and S2 showed similar LST distributions, except urban areas. The variance of S1 LSTs is quite a lot higher than S2 in most areas in the daytime. S1 could simulate the temporal pattern of daily LSTs accurately.

In the daytime, extremely high LSTs were well predicted by S2, as opposed to S1; however, relatively low LSTs were better predicted by S1. S1 also simulated the rapid temperature changes (i.e. rainy days) better than S2.

Two Scheme Combinations (SC)

- We further examined the combination of the two schemes (S1 and S2). In daytime, the LSTs developed from S2 were used for days with relatively high LSTs, whereas S1 was used for days with lower temperatures. For nighttime, the average of S1 and S2 LSTs was used.
- When the two schemes were combined (SC), the proposed all-weather LSTs resulted in an average R² of 0.82 and 0.74 and with RMSE of 2.5 °C and **1.4 °C for daytime and nighttime**, respectively, compared to the in situ data.

LOOCV validation results for S1, S2 and SC

	Daytime (All-weather)					Nighttime (All-weather)						
Station	R ²			RMSE (°C)		R ²			RMSE (°C)			
	S 1	S 2	SC	S 1	S2	SC	S 1	S 2	SC	S 1	S 2	SC
1	0.78	0.77	0.82	2.2	2.5	1.9	0.76	0.73	0.75	1.1	1.2	1.2
2	0.75	0.72	0.79	2.5	2.3	2.3	0.73	0.68	0.72	2.0	1.8	1.9
3	0.80	0.73	0.82	3.2	5.0	2.6	0.73	0.71	0.73	1.7	1.7	1.7
4	0.78	0.74	0.79	2.0	3.0	2.1	0.76	0.76	0.77	1.2	1.3	1.2
5	0.83	0.79	0.81	4.1	3.0	3.3	0.70	0.73	0.73	1.9	1.7	1.7
6	0.83	0.80	0.85	2.9	5.5	3.0	0.66	0.67	0.68	1.4	1.5	1.4
7	0.83	0.81	0.82	2.2	1.7	2.1	0.74	0.74	0.75	1.0	1.0	1.0
8	0.82	0.81	0.83	2.1	3.2	2.2	0.71	0.71	0.73	1.1	1.2	1.1
9	0.84	0.83	0.82	2.8	4.5	2.5	0.73	0.73	0.74	1.5	1.5	1.5
10	0.82	0.76	0.80	2.3	4.3	2.6	0.74	0.76	0.76	1.3	1.3	1.2

Conclusion

This paper demonstrates the ability of the two different schemes to produce all-weather dynamic LSTs. The strategy proposed in this study can improve the applicability of LSTs in a variety of research and practical fields, particularly for areas that are very frequently covered with clouds.